

ICE BRIDGE: Photogrammetric Camera

Toni Schenk, Ohio State University
schenk.2@osu.edu

Bea Csatho, University at Buffalo
bcsatho@buffalo.edu

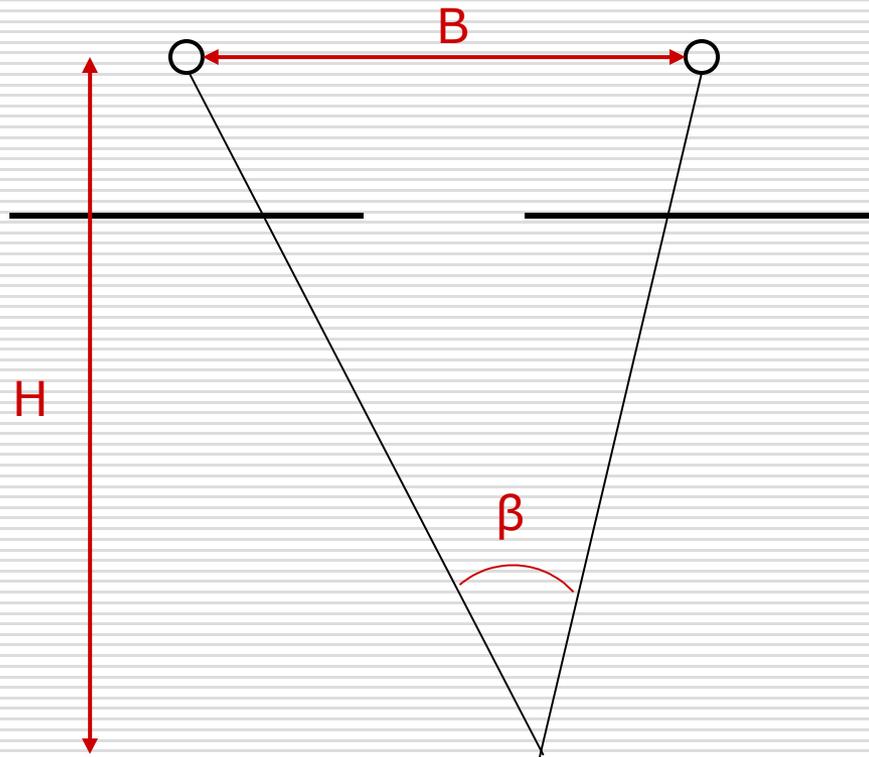
Science Objectives

1. Precise surface reconstruction and surface roughness analysis
 2. Determine velocities and strain rates from repeat flights
 3. Determine control information for registering various sensors
-

Specifications

- To meet science objectives we need:
 - Ground Sampling Distance $GSD = 0.1$ m for low altitude flights
 - Swath width $SW = 300$ m (comparable to ATM swath width) → 3000 pixels across flight line
 - Stereo capability for determining surface elevations, precision of elevations 0.1 m → B/H ratio = 0.6
-

Base/Height (B/H) Ratio



Camera Requirements

- Metric properties: after calibration interior orientation should remain constant
 - FOV
 - To satisfy B/H ratio: $\sim 60^\circ$
 - To satisfy SW (ATM scan angle): 40° k
 - Dynamic range: 12 – 14 bits k
 - Resolution: 3000 pixels cross flight
-

Camera Options

- Photogrammetric cameras (frame or multi-line)
 - Require stabilized platform and port at least 400 mm diameter
 - No ports available → not an option 2009
 - High-resolution commercial cameras
 - Canon EOS 5D Mark II (~21.1 MPixels)
 - Nikon D3X (~24.5 MPixels)
-

Proposed Camera

- Canon EOS 5D Mark II
 - Available from Cirrus Digital Systems
 - Practical experience from NASA High Altitude Mapping Program (John Arvesen)
 - Issues:
 - Metric stability
 - Geocoding (synchronization with Applanix)
-

Possible Configuration

- Canon EOS 5D Mark II has resolution of 5616 x 3744 pixels, nominal pixel size = 6.2 micron, comes with different focal lengths
 - Mount long side along flight direction
→ 3744 pixels cross track
 - $B/H = 0.6 \rightarrow B = 300 \text{ m}$ ($H = 500 \text{ m}$)
 - → exposure rate $\sim 2 \text{ sec/frame}$
-

Concluding remarks

- Canon best compromise under current circumstances
 - Good chance to meet science objectives
 - 2009 camera mission will provide most valuable data and experience
 - Exact details about camera configuration still under discussion
-